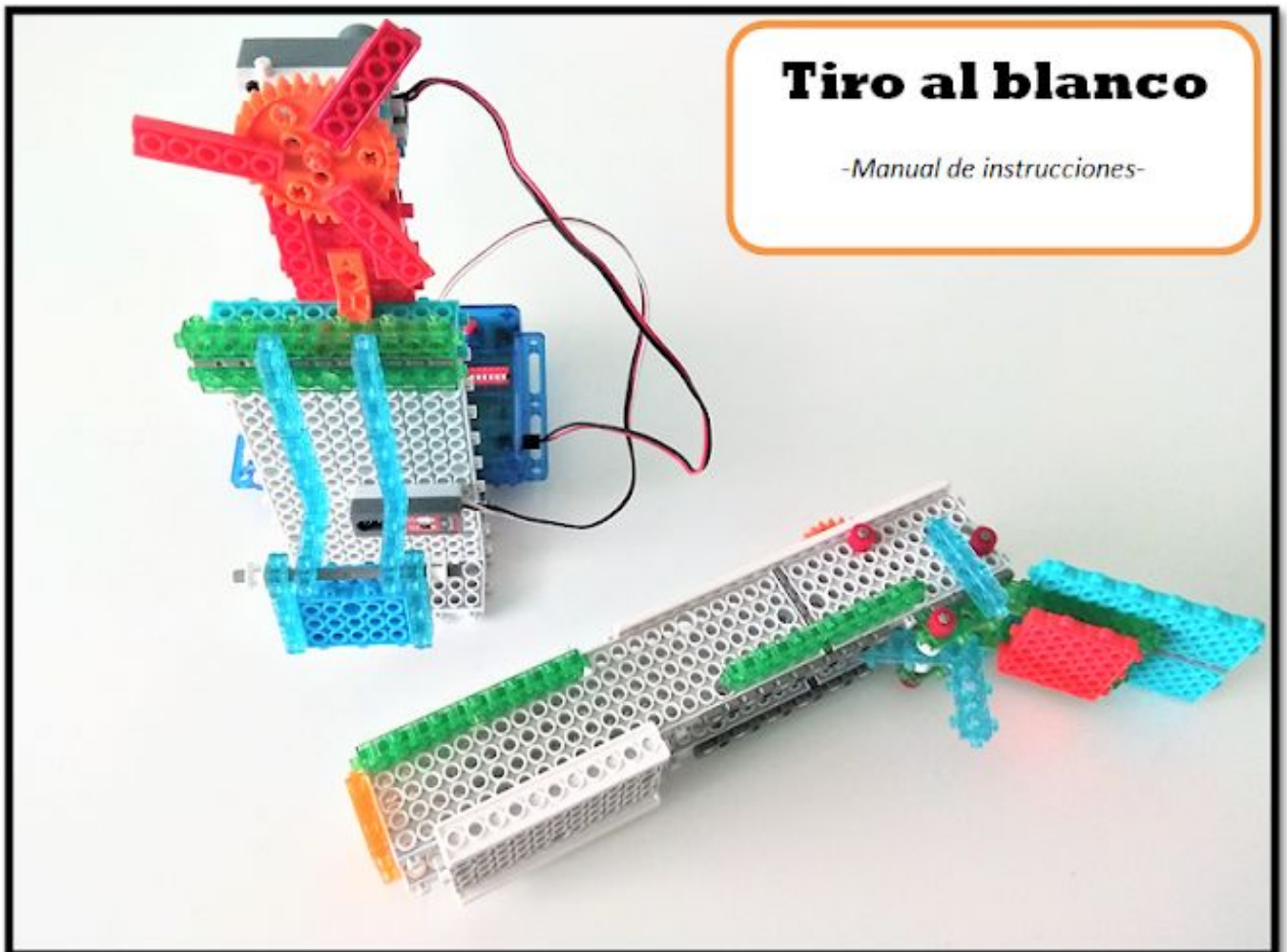




my robot time

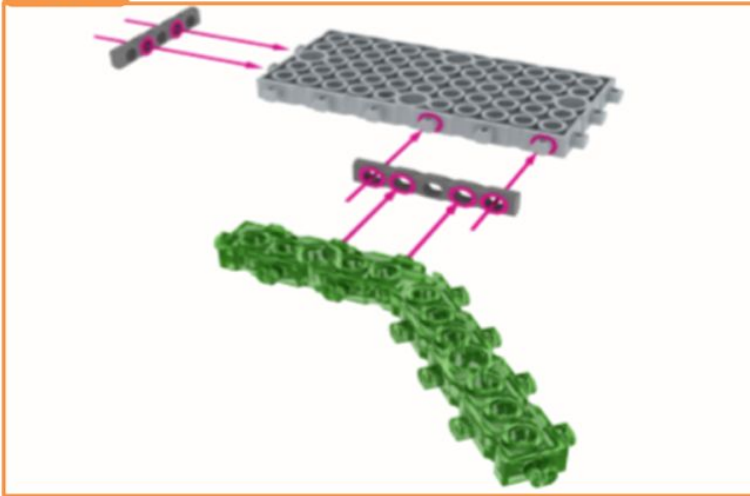
CONSTRUCCIÓN N° 14

Tiro al blanco

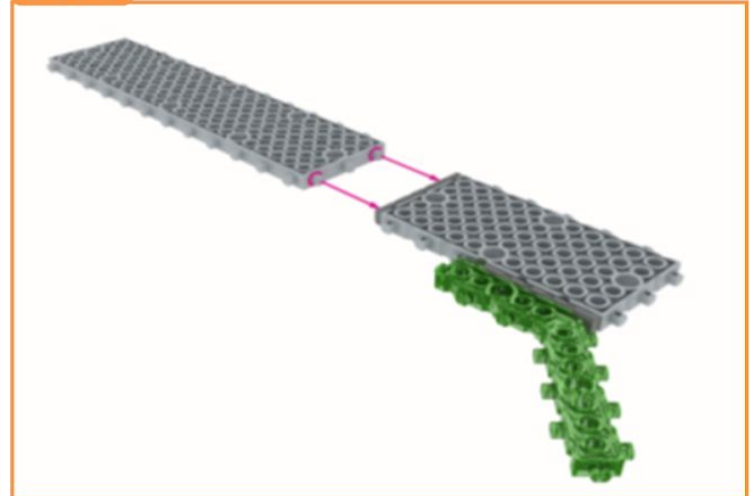




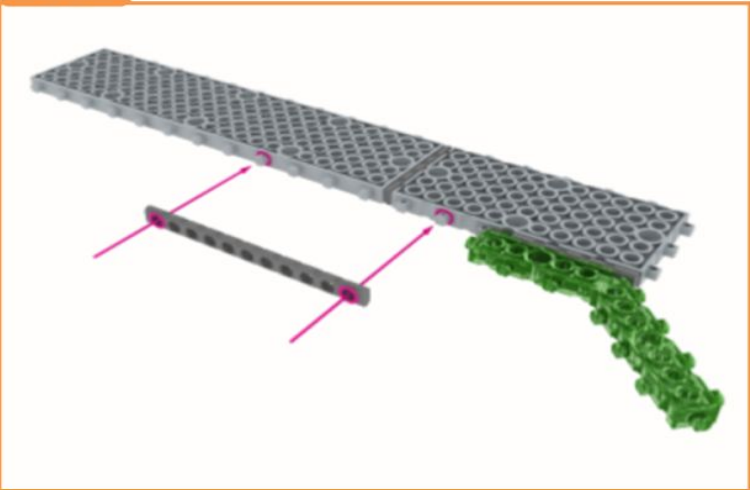
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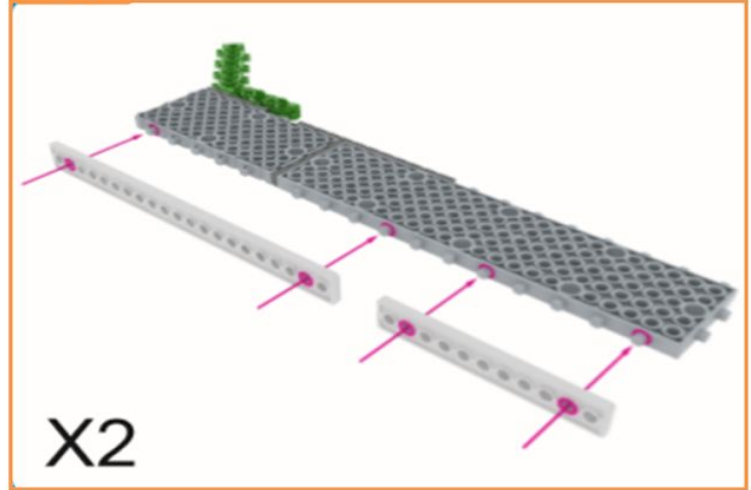
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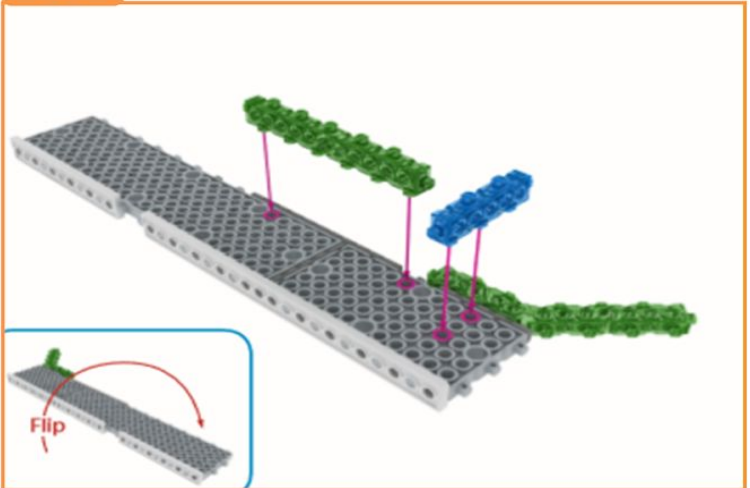
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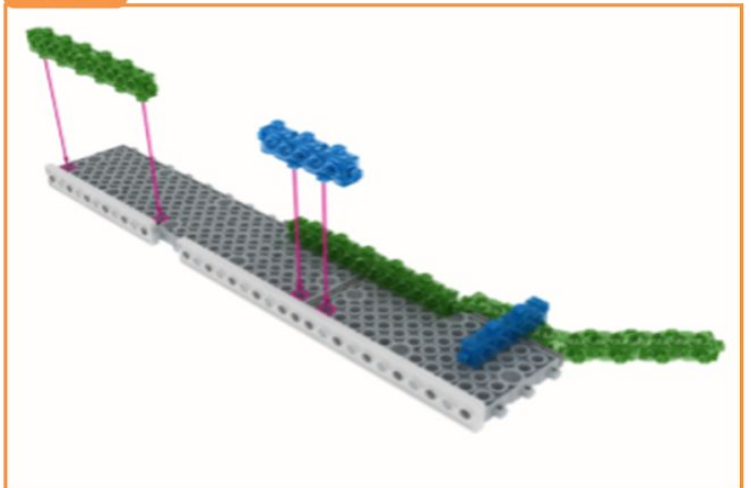
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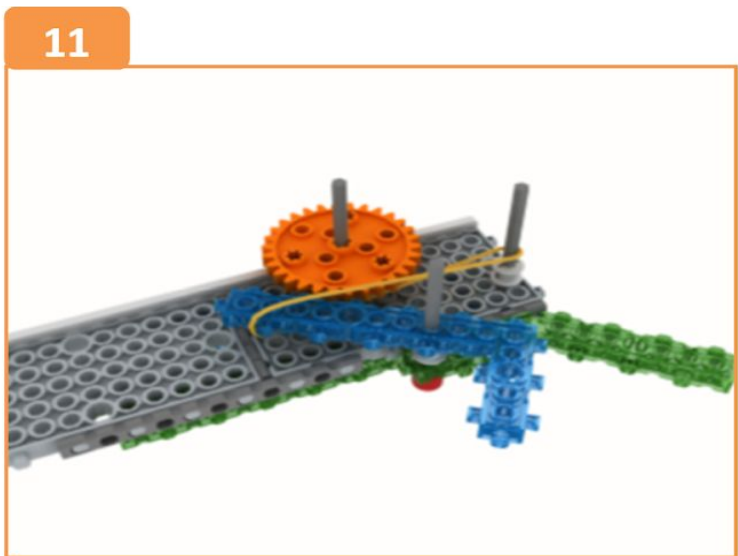
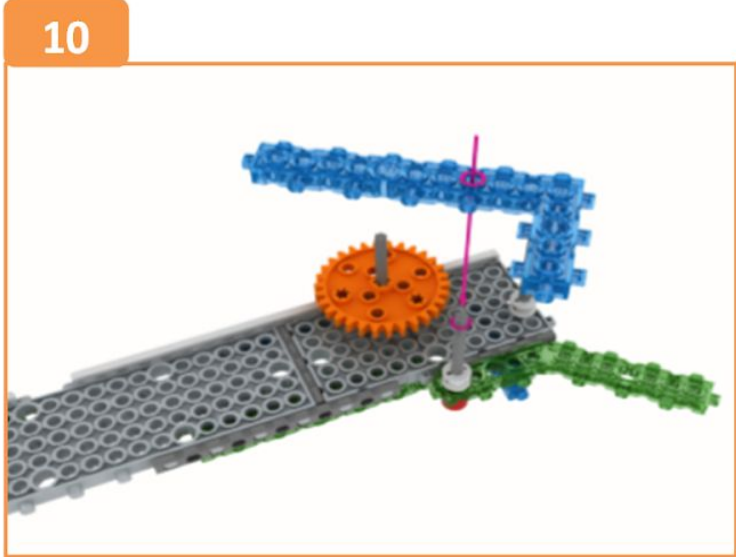
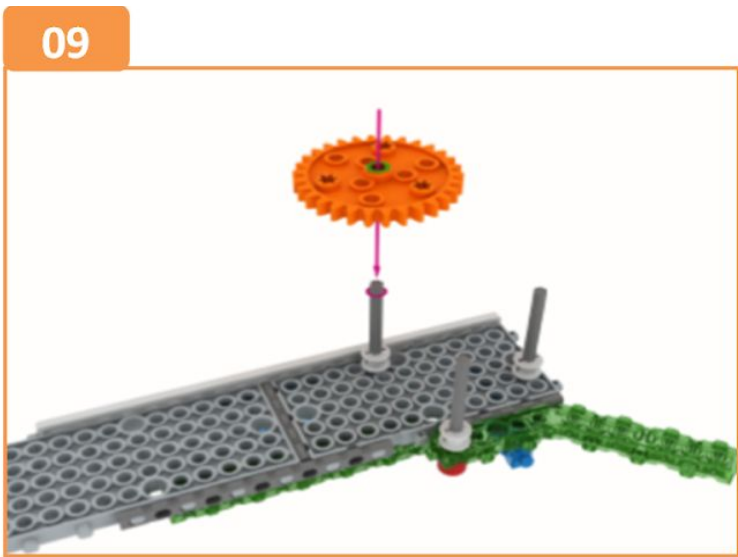
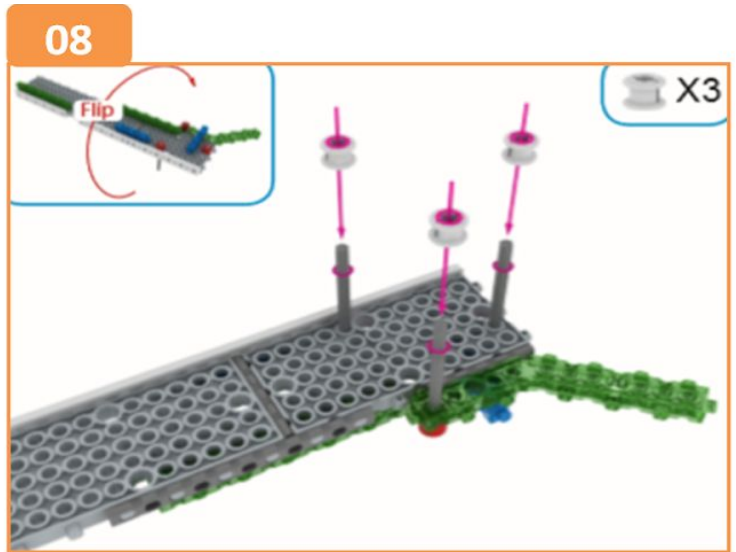
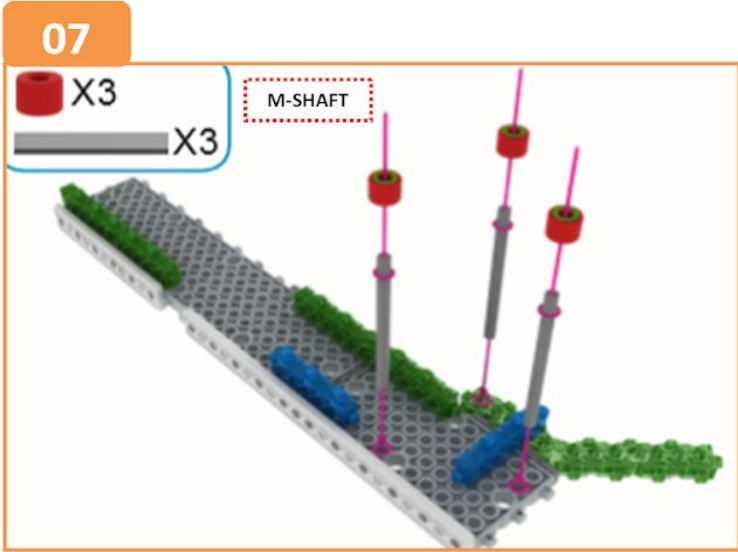


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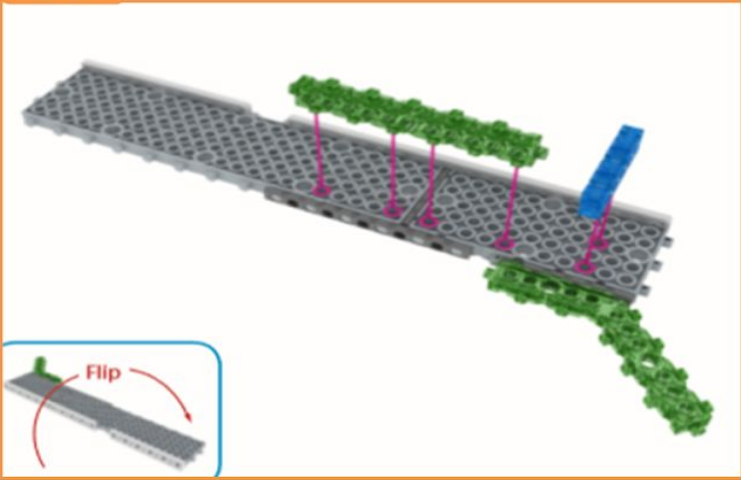
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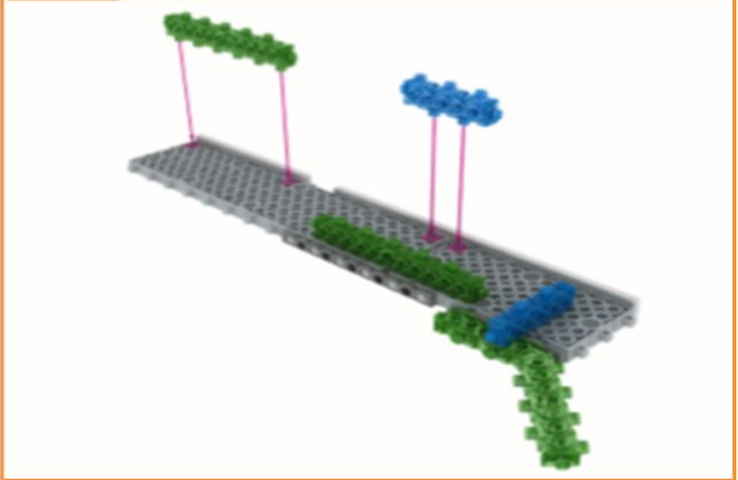




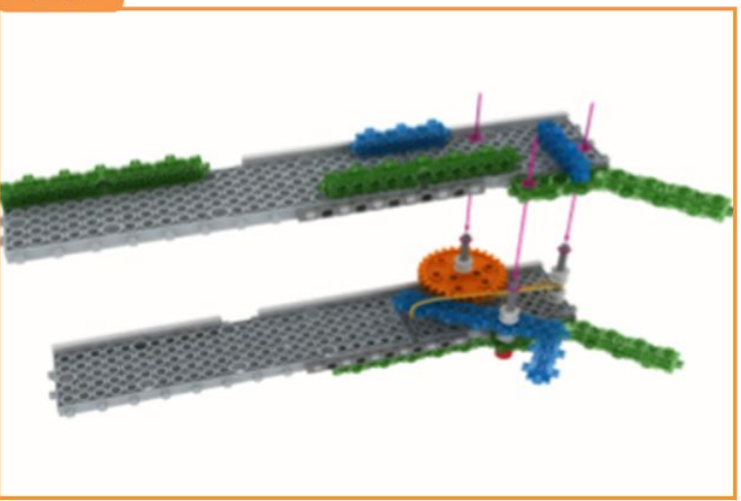
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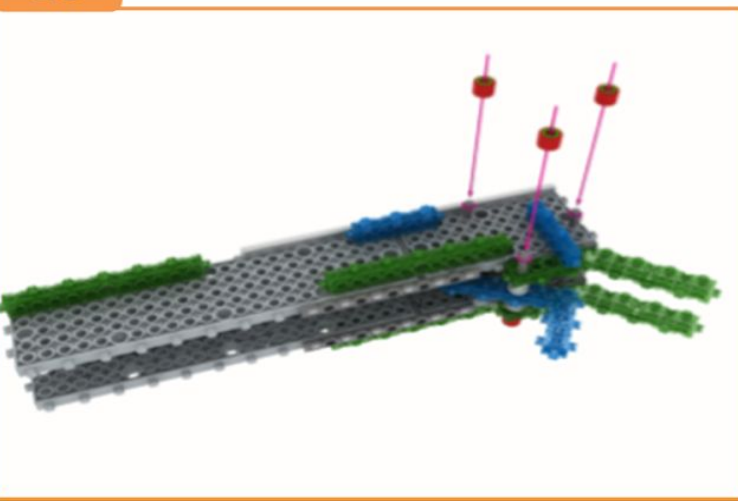
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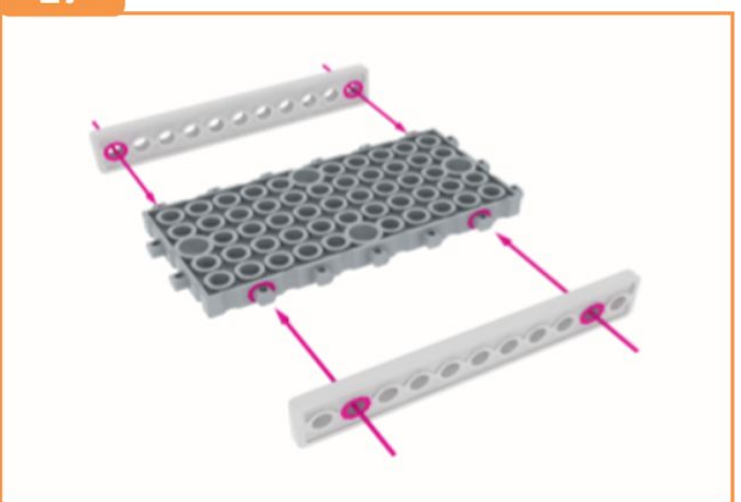
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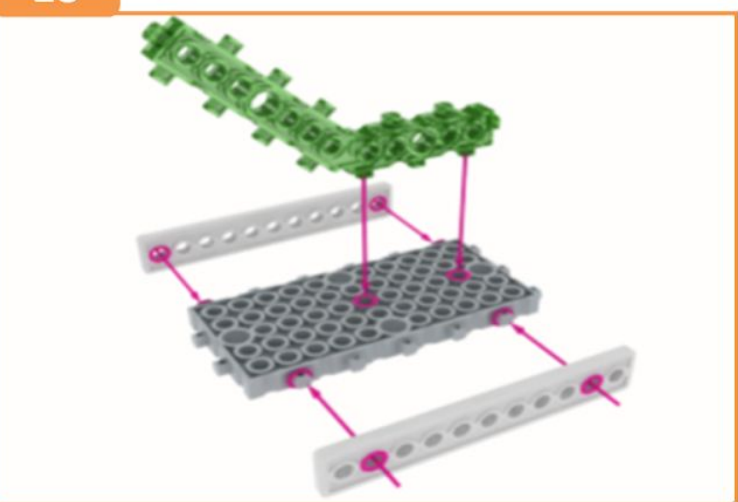
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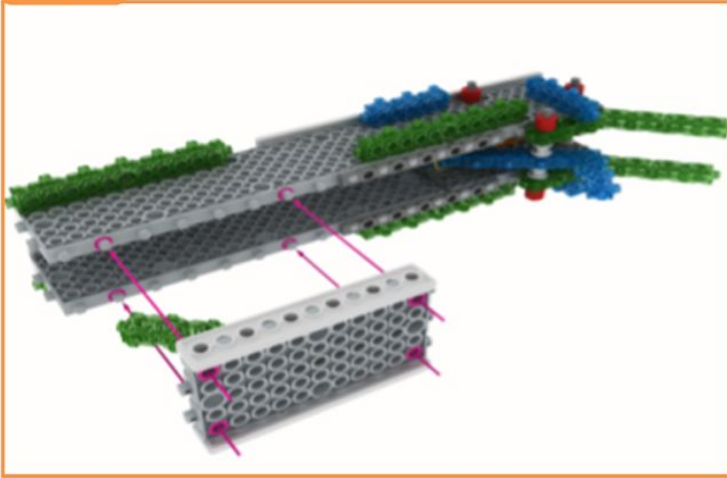


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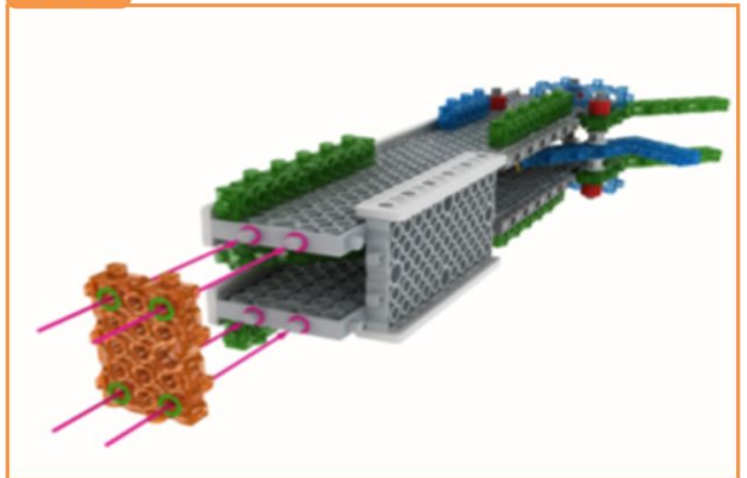




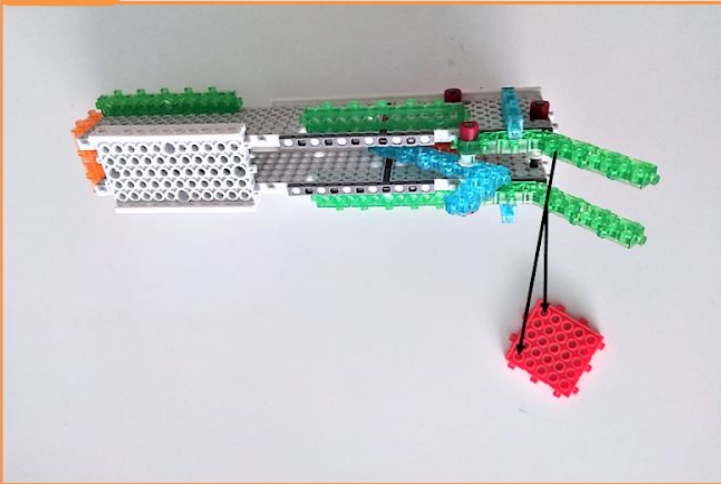
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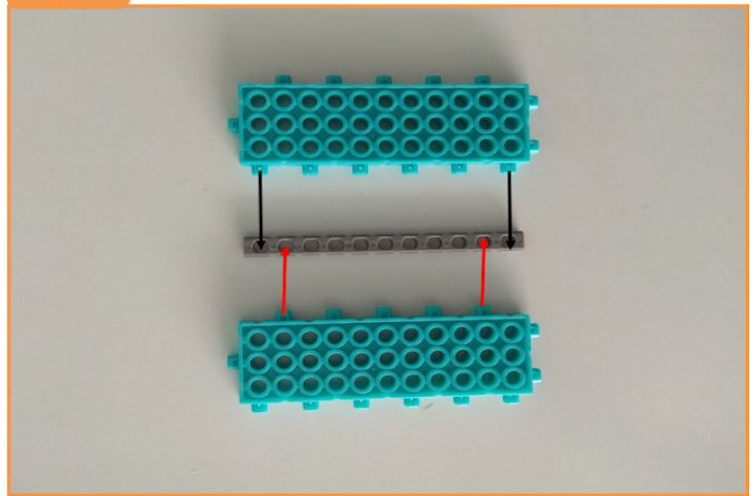
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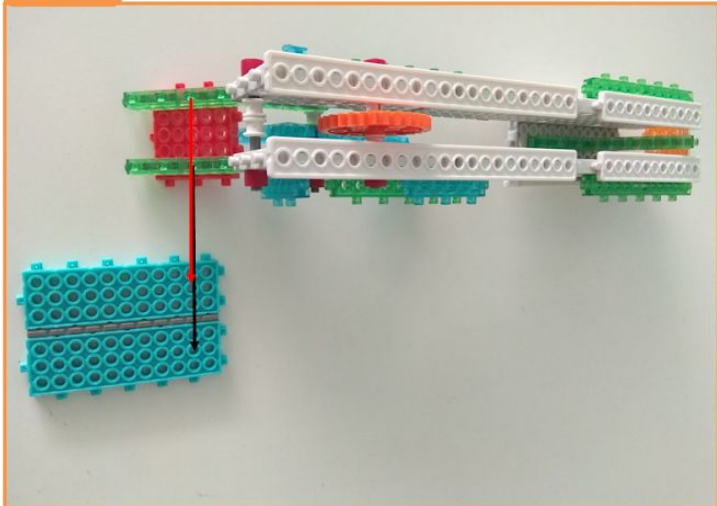
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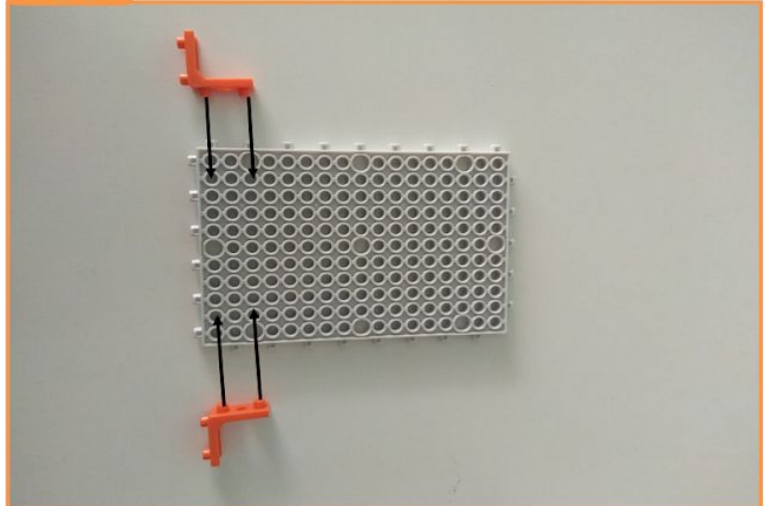
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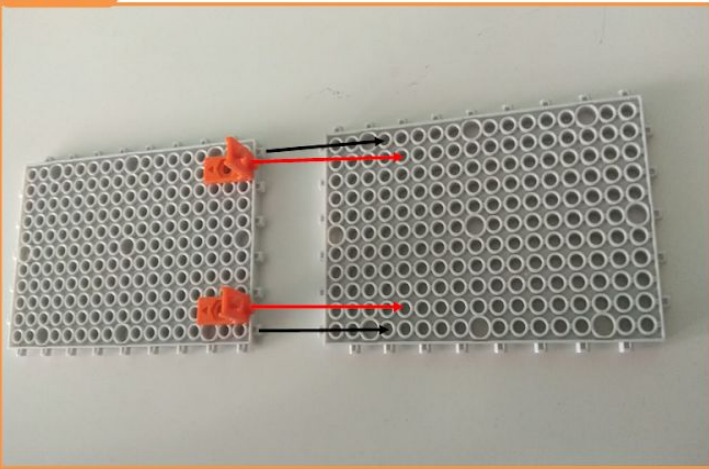


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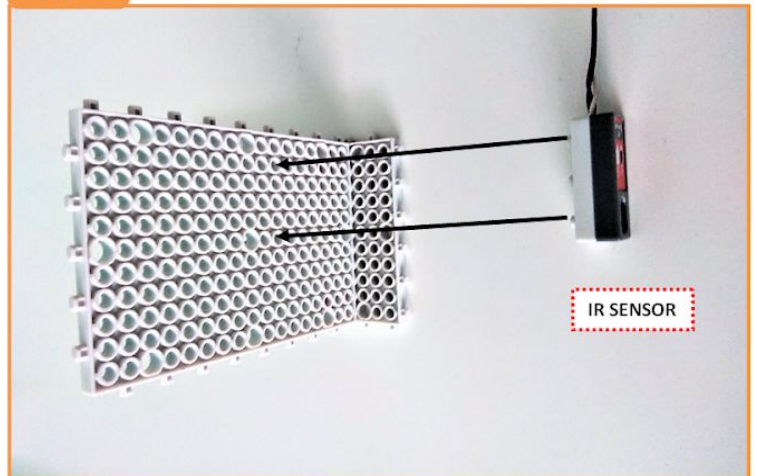




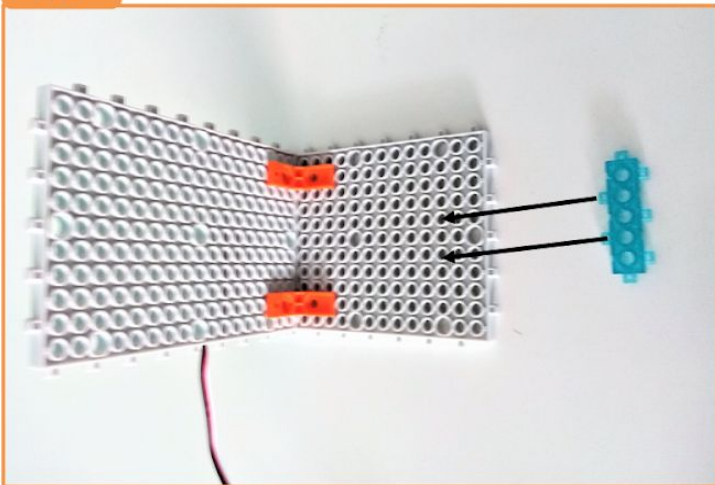
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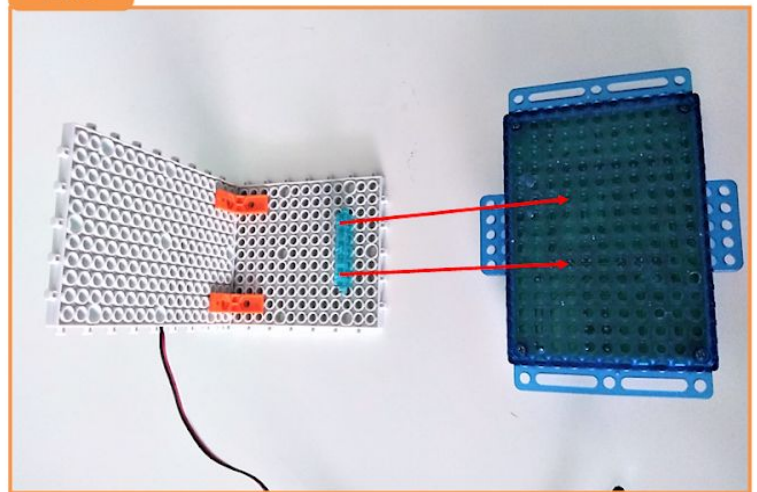
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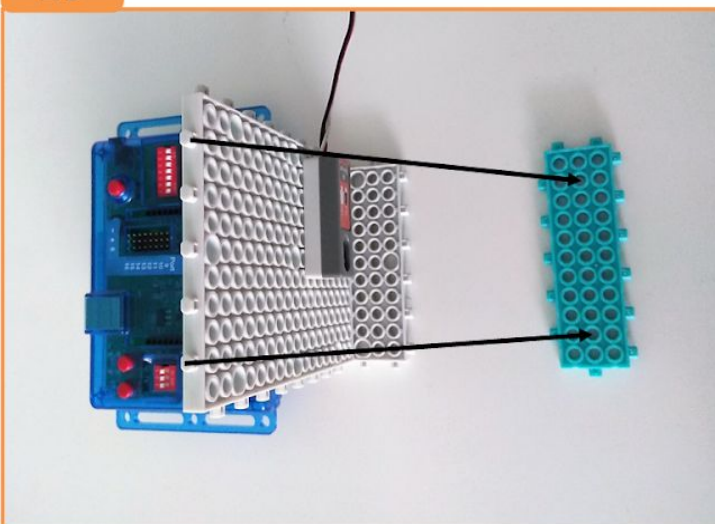
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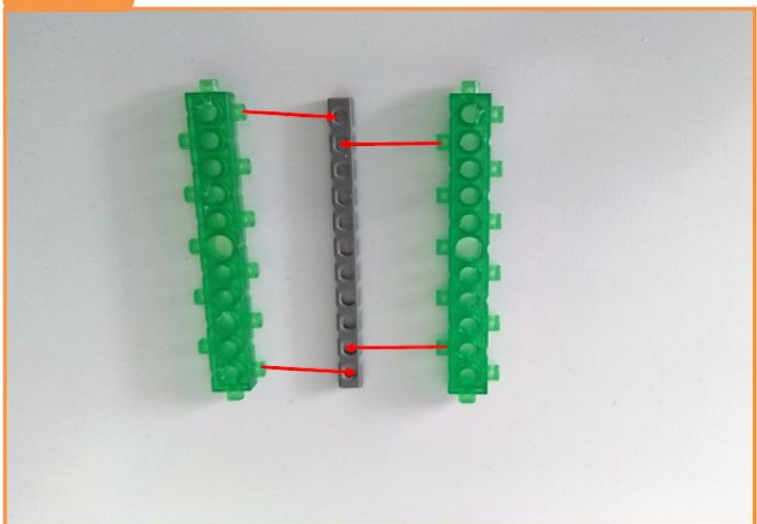
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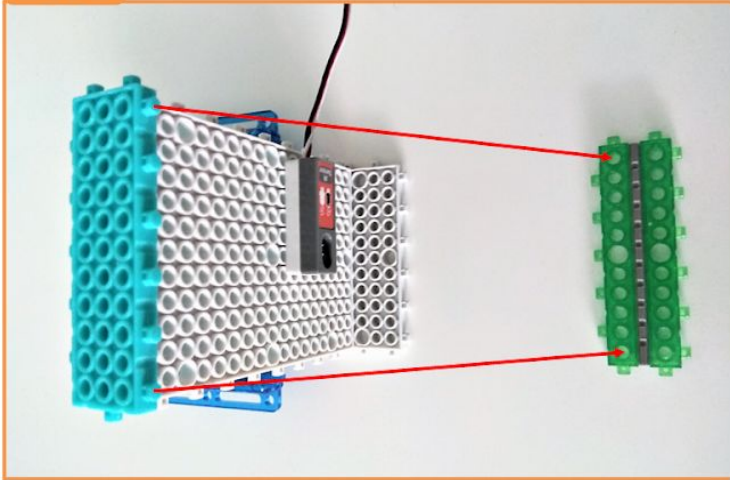


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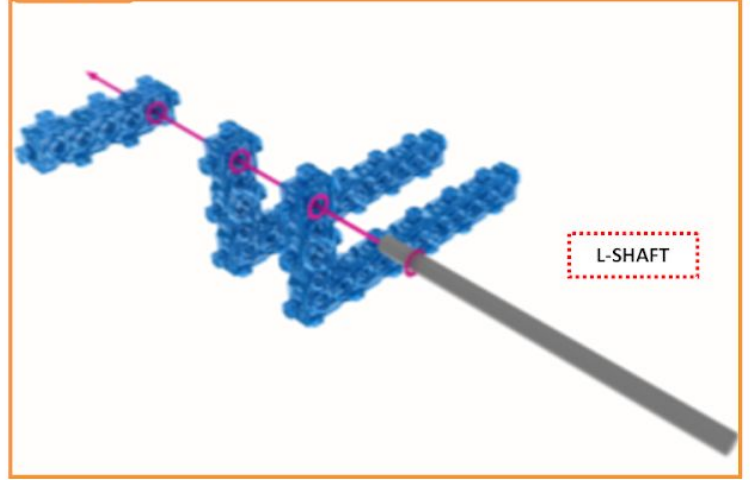




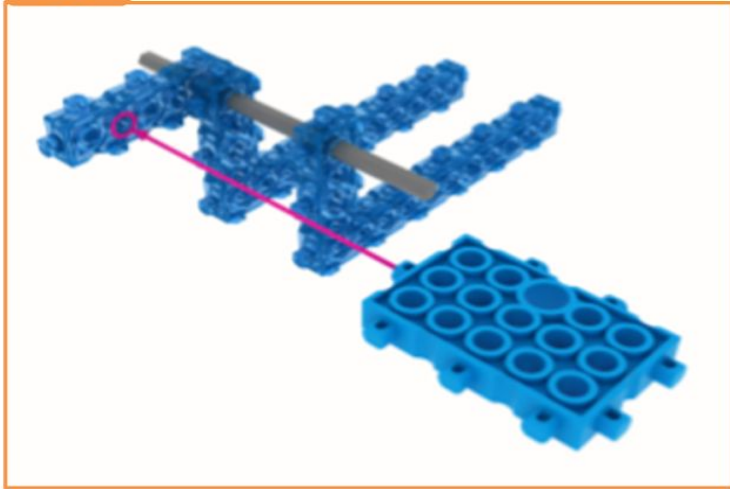
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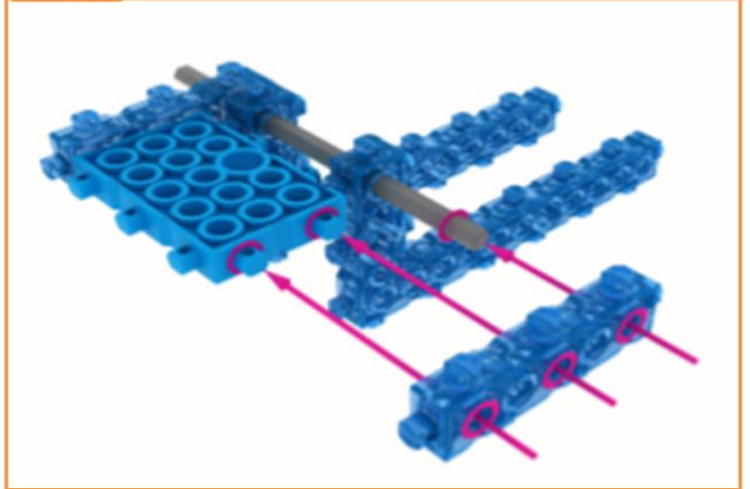
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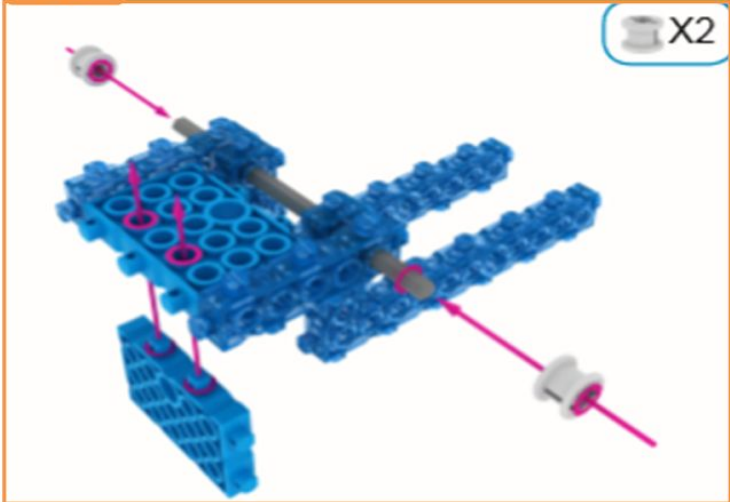
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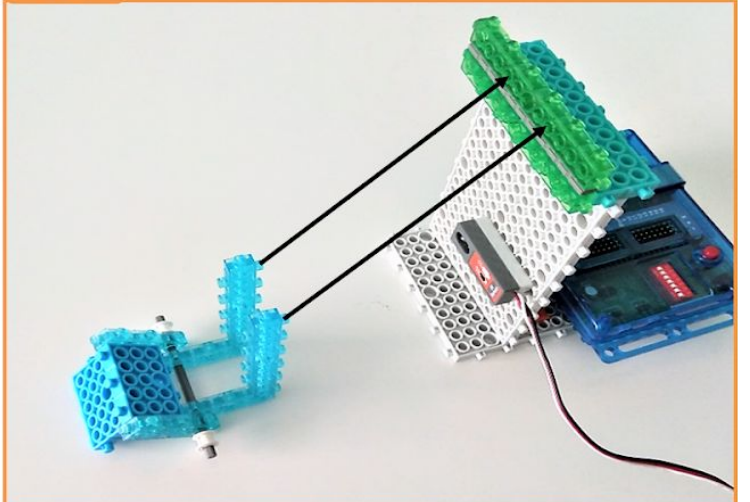
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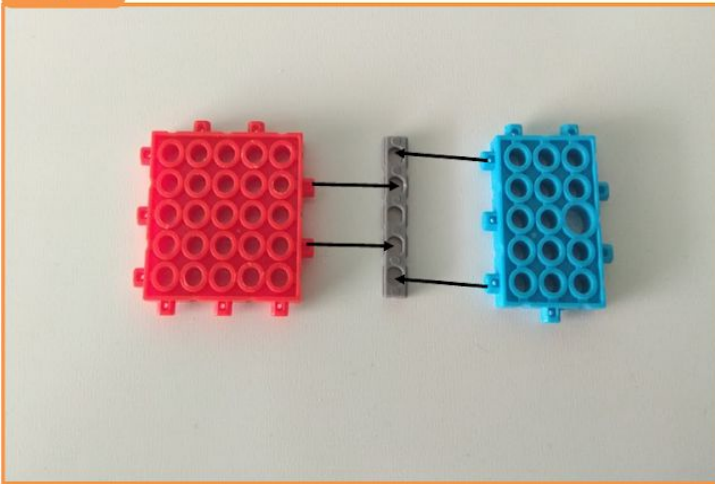


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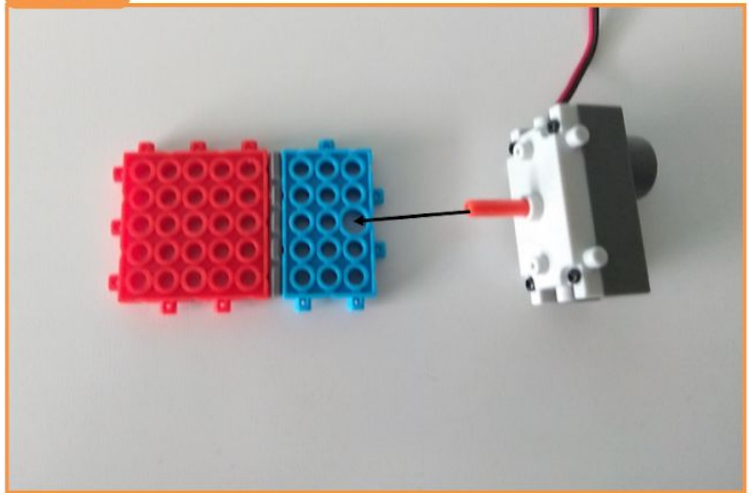




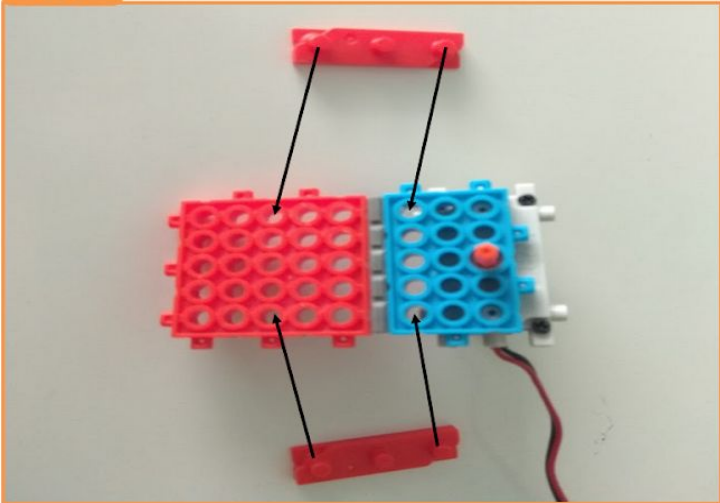
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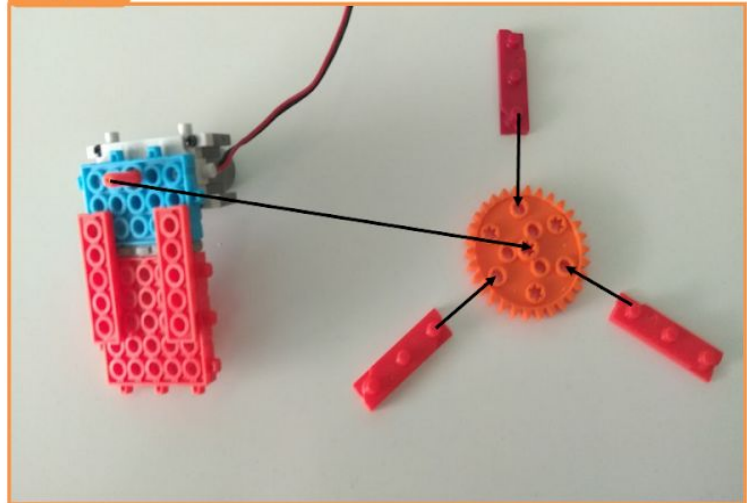
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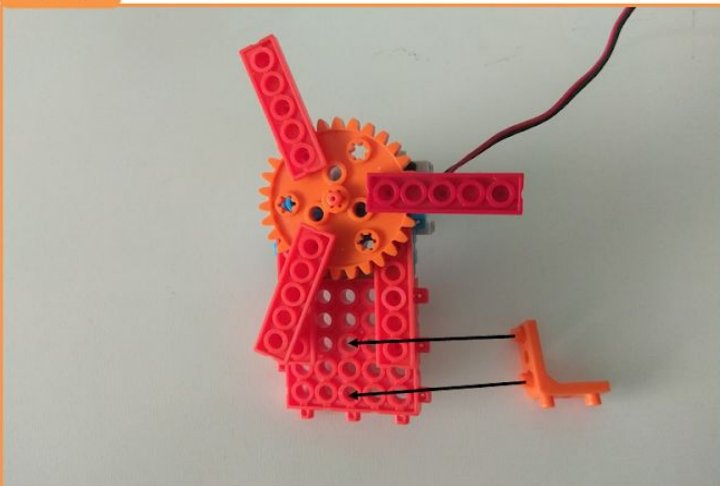
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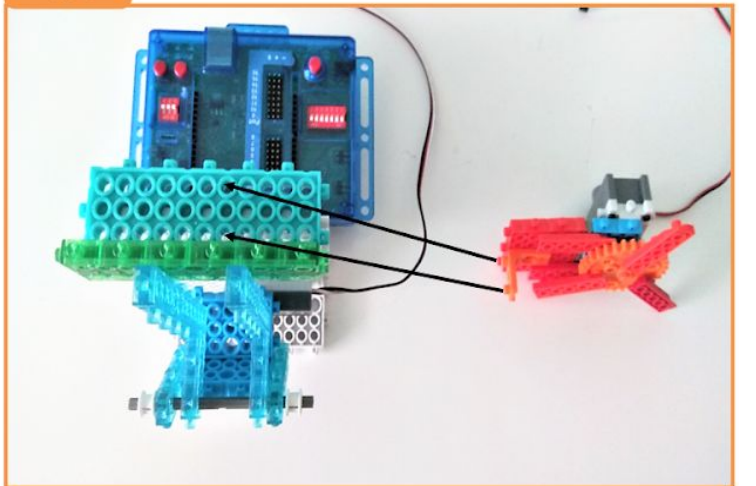
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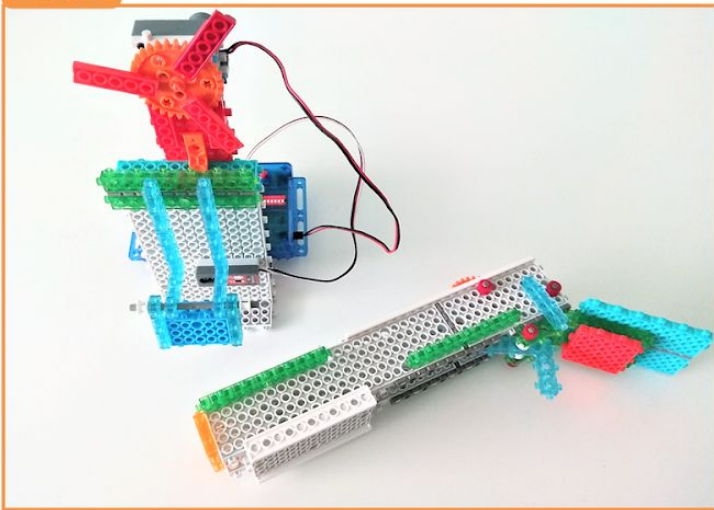
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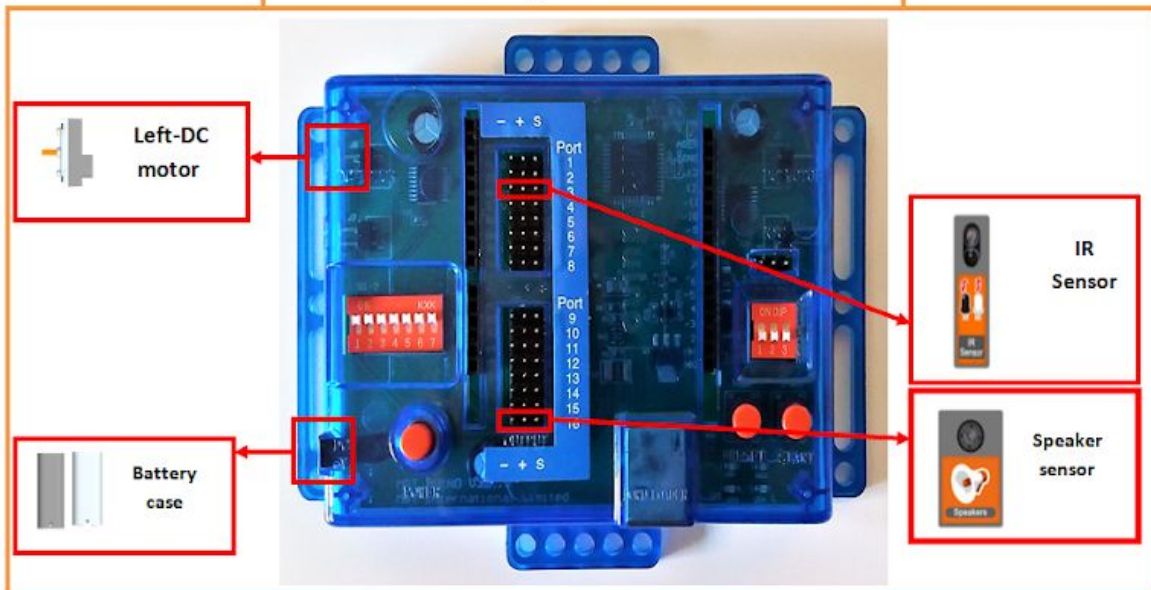
42



OK



Connecting the main board



SELECCIONAR EL PROGRAMA

- 1° Conectar las pilas a la placa a través del portapilas
- 2° Encender la controladora pulsando el botón POWER.
- 3° Conectar el altavoz en el PIN 16.
- 4° Pulsar el botón START nueve veces (nota RE+) y esperar 3 segundos hasta que comience a ejecutarse.